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## **Novel results on SCTP multihoming performance in native IPv6 UMTS-WLAN environments**

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**Abstract:** Multihoming is one of the most attractive features of stream control transmission protocol (SCTP) aiming to make this prosperous transport scheme competitive in mobile environments when the mobile hosts are equipped with multiple interfaces. The complementary characteristic of the 3G universal mobile telecommunications system (UMTS) and wireless local area network (WLAN) architectures motivates operators to integrate these two successful technologies. Recently spreading wireless devices are increasingly provided with multiple networking interfaces such enabling end-users to access internet services using e.g., the WLAN's higher bandwidth wherever available, and connecting to the UMTS network in other cases. This paper investigates the performance of multihomed SCTP hosts through extensive experimental studies in such an integrated heterogeneous environment. In order to do this, we designed and implemented a real native IPv6 UMTS-WLAN testbed equipped with novel IPv6-based mobile technologies, such providing ideal conditions for SCTP multihoming performance analysis. In this testbed architecture we analysed numerous settings to measure the handover behaviour of the protocol in terms of handover effectiveness, link changeover characteristics, throughput and transmission delay. As our results show, accurate SCTP parameter setup can significantly decrease the handover delay and eliminate the data transmission interrupts.

**Keywords:** stream control transmission protocol; SCTP; multihoming; performance evaluation; IPv6; universal mobile telecommunications system; UMTS; wireless local area network; WLAN; testbed; vertical handover; heterogeneous environment; transport layer mobility.

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## 1 Introduction

Mobility is becoming increasingly popular feature for the internet users; however, the developers of the early network protocols did not take into consideration this possibility. The internet was a static network, where the hosts were connected through one specific link and identified with a unique IP address. The new mobile access technologies have totally changed this attitude. For the next-generation internet, one of the most essential requirements is to make the roaming possible without losing the connection. Demand for anywhere, anytime communications has been increasing recently. Moreover, with the extensive growth of the internet and mobile/wireless systems, the user demand for continuous data access caused the introduction of many different kinds of access technologies. Therefore, future telecommunication architectures could easily appear as an integration of multiple wireless access technologies (e.g., Bluetooth, UMTS, WLAN, WiMAX, etc.). By enabling multi-access in mobile systems, redundancy and fault tolerance can be achieved. Hosts equipped with multiple network interfaces can be connected to the internet via different ISPs, such failures in one network cannot easily break ongoing communication sessions: hosts are capable of switching over to another connection. Moreover, if both connections are active at once, but higher packet loss and delay is experienced on one path, multihoming capabilities can be used to hand over current sessions to the connection offering better values of quality of service (QoS) parameters.

The applied internet protocols and network architectural structure have to be modified and extended to support all requirements of the above advanced networking features. The key problem is how to manage the frequent IP address changes, i.e., how to hand over ongoing communication processes from one interface (or path) to another active interface with the minimal disruption. Mobility and multihoming supporting schemes were designed to handle this question.

Mobility and multihoming support can be provided in different layers of the ISO/OSI architecture (Ratola, 2004; Eddy, 2004). Mobile IP (Johnson et al, 2004) with multiple

care-of addresses (MCoA) (Wakikawa et al., 2008) extension is a Layer 3 solution, while several proposals exist also in the transport (Stewart, 2007) and even in the application layer (Rosenberg et al., 2002). A good example for a novel solution between the latter two traditional layers is the host identity protocol (HIP) (Moskowitz et al., 2008). To introduce all of the possible solutions and their own advantages and disadvantages is out of scope of this paper. However, a good survey with an extensive analysis can be found in Deguang et al. (2006) anticipating a multi-layered approach for advanced mobility support and suggesting the transport layer as the main candidate for internet mobility and multihoming support.

In this paper, we focus on SCTP and its multihoming and multi-streaming performance over heterogeneous IP networks, more precisely over native IPv6 UMTS-WLAN environments. The importance of building our SCTP experiments on a native IPv6 architecture resides in the fact that IP is considered as the best solution to integrate heterogeneous wireless access networks, and IPv6 will actually be the main networking protocol of the next generation internet. Nowadays, the most widespread IP version (IPv4) is based on a scheme where the devices are identified by 32-bit long addresses. However, due to the continuously growing internet penetration it is predicted that all currently available IPv4 address blocks will be allocated by the year 2011 (IPv4 Address Report). However, there are several methods to overcome this problem (like expanding application of NATs or introducing a secondary market for already allocated but currently unused IPv4 address blocks), it is unquestionable that the most future-proof strategy for the internet is the deployment of IPv6. The fundamentals are the same in both versions (v4 and v6), but IPv6 introduces a much larger address space (128-bit long addresses are applied) allowing convenient implementation of internet applications requiring point-to-point connections between hosts. In addition, IPv6 also provides integrated security (IPSec), QoS, elaborated auto configuration and multicasting, and extensions supporting Layer 3 mobility and multihoming. Generally speaking, IPv6 supports ‘always on’ paradigm and peer-to-peer type communication in a lot more improved way than IPv4; such providing more seamless and rich communication of users in future heterogeneous, all-IP mobile and wireless architectures.

In order to study multihoming in an integrated, all-IP heterogeneous mobile environment, we realised a native IPv6 UMTS-WLAN testbed and examined the main performance measures of a SCTP-based Layer 4 mobility/multihoming architecture.

The rest of the paper is organised as follows. Section 2 presents related works giving an overview of initial and ongoing research efforts on SCTP multihoming. In Section 3 theoretical background of our work is introduced including the basics of multi-access and multihoming, SCTP, and UMTS-WLAN interworking. Section 4 is devoted to introduce our native IPv6 UMTS-WLAN testbed architecture designed to perform practical SCTP multihoming evaluation, while Section 5 shows and explains the experimental results. Finally, Section 6 concludes the paper and sketches our future work.

## 2 Related work

In this paper, the behaviour of SCTP and the effect of the protocol’s main parameters (*HB.Interval*, *RTO.Min*, *RTO.Max*, etc.) on SCTP multihoming performance are evaluated in a real-life native IPv6 UMTS-WLAN heterogeneous architecture.

Previous works examining SCTP mobility and multihoming performance are mainly based on simulations (Chang et al., 2004; Jungmaier and Rathgeb, 2006; Duke et al., 2003) or using emulator tools to imitate the behaviour of different type of networks (Ravier et al., 2001a; Ha et al., 2005a; Österdahl, 2005). Some new ideas and SCTP extensions were also proposed. A new method was investigated in Ma et al. (2004), in order to facilitate seamless vertical handover between wide area cellular data networks such as UMTS and WLANs using SCTP, but the evaluation was performed also using simulations. In Ma et al. (2007), the authors presented and analytically evaluated a novel error recovery scheme to improve SCTP's mobility supporting capabilities in heterogeneous wireless networks. Fu and Atiquzzaman (2005) also provided an analytical model for studying the performance of SCTP multihoming. Their proposed model has been validated against simulations. Budzisz et al. (2007) presented analytical calculations as well in order to have more accurate estimation of the failover time in SCTP multihoming scenarios.

SCTP standard does not allow using multiple paths simultaneously; however, this possibility can gain significant improvement in overall data transmission bit rate. Numerous proposals are available to overcome this issue. Ye et al. (2004) introduced an independent per path congestion control principle for standard SCTP, while in Iyengar et al. (2006) a similar solution is presented with load sharing techniques.

There are also attempts to analyse the behaviour of multi-homed SCTP associations and stalls (Noonan et al., 2006), and also to look at other issues related specifically to SCTP multihoming (Jungmaier et al., 2002; Iyengar et al., 2003) or to special use-cases of SCTP (Charoenpanyasak and Paillassa, 2007).

Some of the first previous works dealing with SCTP mobility and multihoming performance evaluation in real life testbeds were Ravier et al. (2001b), Ha et al. (2005b) and Shi et al. (2003), where authors mainly confined their work to study how SCTP deals with packet loss and throughput in quite simple multihoming experiments. Shi et al. (2004) investigated the key scenarios for multi-access and multihoming based on an analytical model, and also performed some SCTP/TCP comparison measurements in GPRS-WLAN architecture. An interesting SCTP testbed was created by Kim et al. (2007). The authors developed a novel IPTV service exploiting the multi-streaming feature of SCTP, and compared their method with TCP- and UDP-based schemes for a variety of network conditions. Practical evaluation of SCTP multihoming was performed by Siddiqui and Zeadally (2006). The authors discussed the design and performance issues related to SCTP multihoming operation in a real Ethernet-WLAN multi-network architecture. Fallon et al. (2008) examined SCTP switchover performance in a pure WLAN environment and showed that with the default parameters, SCTP implementations behave in a counterintuitive manner allowing more time for switchover when network conditions degrade. Also a pure WLAN testbed was used by Wakikawa et al. (2006) in order to present a smooth handover scheme for mobile IPv6 based on SCTP failover mechanism. Emma et al. (2006) and Dainotti et al. (2007) introduced experimental studies on SCTP in wired (Ethernet), wireless (WLAN) and heterogeneous (wired/wireless) scenarios in terms of throughput and jitter, and also compared SCTP with UDP and TCP considering different packet rates.

However, the above efforts focus on measuring SCTP multihoming performance issues, examining specific protocol extensions and studying handover mechanisms, rather than providing extensive practical evaluation of SCTP in an integrated heterogeneous

testbed architecture, with support of the next generation IP protocol (IPv6) for enabling unlimited peer-to-peer communication in the future ‘internet of things’ world.

### **3 Background**

As the background of our work we first briefly overview the main advantages of multi-access and multihoming followed by the basics of SCTP including some tools for providing efficient multihoming support. Finally, some relevant UMTS-WLAN interworking scenarios will be discussed in order to show the different levels of complexity.

#### *3.1 Benefits of multi-access and multihoming*

New equipments integrate several access technologies in order to increase bandwidth availability or to select the most appropriate access technology according to the type of flow or choices of the user. A multi-access endpoint determinates a host with several network interfaces, however, to manage these interfaces a novel feature called multihoming support must be introduced to efficiently control these interfaces for improved connectivity.

Multihoming is an advantageous technique to increase the reliability of the end-to-end connection, because it makes possible to reach the multihomed host on more than one IP address. If the communicating endpoints and the IP network are configured in such a way that traffic from one node to another travels on physically different paths (different sub-networks and thus, different destination IP addresses are used), associations become tolerant against physical network failures. When one of the interfaces/paths becomes unavailable, the other paths are still ready to deliver data. Besides, multi-access provides ubiquitous access to offer an extended coverage area for the mobile hosts. It is also a good opportunity to spread network traffic load among several routes. This is achieved when traffic load is distributed simultaneously among different connections.

In order to efficiently manage the traffic load on the host interfaces, the corresponding paths must be monitored. When the condition of the actual interface/path is getting worse or fail, a new interface should be assigned for the connection. One of the most important issues is to change the primary path seamlessly. The endpoint must recognise the link failures as soon as possible and change the active IP address, but the handover delays or temporal channel errors should not cause the change of the primary path. The IP change trigger may depend on several protocol settings. It must be defined when should a path considered broken. The number of retransmission attempts, the packet loss ratio and different time constrains may affect the performance of the interface/path changes.

#### *3.2 SCTP*

Stream control transmission protocol (SCTP) is a general purpose transport protocol for the internet, described in RFC 4960 (Stewart, 2007). Similarly to transmission control protocol (TCP), SCTP also provides connection oriented, reliable and ordered delivery of

data between two endpoints. The developers of SCTP aimed to create a new transport protocol that would overcome the limitations of TCP and user datagram protocol (UDP). It offers acknowledged error-free non-duplicated transfer of datagrams. Detection of data corruption, loss of data and duplication of data is achieved by using checksums and sequence numbers. In order to provide reliability, a selective retransmission mechanism is applied. SCTP can also be used for applications where monitoring and detection of loss is required. For such applications the SCTP failure detection mechanisms will actively monitor the session. These mechanisms are also used to manage the SCTP handover process in case of multihomed hosts.

SCTP uses an end-to-end window based flow- and congestion control mechanism similar to the one that is used in TCP. The congestion control mechanism of SCTP has been modified and adapted for multihoming. SCTP uses an additive increase, multiplicative decrease (AIMD) algorithm, similarly to TCP. SCTP endpoints may be reachable by more than one transport address through different data paths. For each possible path a discrete set of flow- and congestion control parameters is kept.

The major features that SCTP provides are multihoming and multi-streaming. The multihoming feature enables to be used for mobility support, without any special router agents or anchor points in the network, while multi-streaming supports multiple independent streams within an association. The detailed introduction of multihoming and multi-streaming are presented in the following subsections.

### 3.3 *SCTP multi-streaming*

SCTP distinguishes different streams of messages within one SCTP association. All the streams (chunks) within an association are independent but related to the association. Each stream has a stream number that is included inside SCTP packets chunk headers. This delivery scheme reduces unnecessary head-of-line blocking between independent streams of messages. In other words, a blocked stream does not affect the other streams in an association. SCTP streams are unidirectional channels, within the data messages are usually transported in sequence. The application may also request a message to be delivered unordered, which can reduce blocking effects in case of message loss, since the reordering mechanism of one stream is not affected by that of another stream that may have to wait for a retransmission of a previously lost data chunk. SCTP multi-streaming is particularly effective in cases, when independent control and data channels are considered in the communication. In TCP, control and data typically share the same connection, which can be problematic because control packets can be delayed behind data packets. If control and data messages are delivered within independent streams, control data could be dealt with in a timelier manner, resulting better utilisation.

### 3.4 *SCTP multihoming*

One of the most important enhancements in SCTP over traditional transport layer protocols is the multihoming capability. A multi-homed host is one that can be reached using more than one IP addresses, usually through more than one network interfaces. This feature allows an endpoint of a SCTP association to be mapped to multiple IP addresses. Among the possible IP addresses, one is selected as primary address, while the primary path is considered as the network path that leads to the primary address. Unless specified otherwise by the SCTP user, an endpoint should always transmit on the primary

path. The sender may change the primary address if the number of failures on the primary path exceeds a certain threshold. In this case the SCTP implementation notifies its upper layer process that the link has become inactive. Retransmissions should be done on different paths as well, so when one link is overloaded, retransmissions do not affect it.

SCTP packets consist of a common header, followed by a variable number of information units, which are named chunks. There are two types of chunks: control and data chunks. Data chunks contain the actual user messages, while control chunks are used to support the peer-to-peer protocol.

If a client is multihomed, it informs the server about all its IP addresses with the INIT chunk's address parameters. Hence, the client is only required to know only one IP address of the server because the server provides all its IP addresses to the client in the INIT-ACK chunk. SCTP is able to handle both IPv4 and IPv6 addresses.

Another important feature of the SCTP regarding multihoming, is the heartbeat mechanism. This mechanism detects failures in idle paths and endpoints. The aim of this mechanism is to detect whether a destination address is active or passive. HEARTBEAT chunks are sent periodically to all idle destinations, and the number of sent HEARTBEAT messages without receipt of a corresponding HEARTBEAT-ACK is maintained. The timing of the HEARTBEAT chunks for destination  $i$  is determined by the  $HB.Interval$  and  $RTO$  (*Retransmission Timeout*) protocol parameters according to the following equation (Stewart, 2007):

$$H_i = RTO_i + HB.Interval(1 + \delta) \quad (1)$$

where  $\delta$  is a random value between  $-0.5$  and  $0.5$  and  $RTO$  is the retransmission timeout for path  $i$ .

An address is considered active if acknowledgement is received from its peer within a defined time period ( $RTO$ ). In this way  $RTO$  is a prediction of the upper limit of round trip time (RTT). Separate  $RTO$  is maintained for each path which is calculated using the smoothed average of the periodically measured RTT ( $SRTT$ ) and the RTT variation ( $RTTVAR$ ). From these,  $RTO$  is computed as (Stewart, 2007):

$$RTO = SRTT + 4RTTVAR \quad (2)$$

If the number of consecutive transmission timeouts exceeds the path maximum retransmission ( $PMR$ ) protocol parameter, it means the address is inactive. Every time when timeout occurs, the  $PMR$  counter is incremented and the value of the  $RTO$  is doubled for that path. If the new  $RTO$  is less than  $RTO.Min$ , it will be set to  $RTO.Min$ , if it is greater than  $RTO.Max$ , it will be set to  $RTO.Max$ . According to the previously presented procedure the delay of the path failure recovery and the handover process can be calculated as follows:

$$\Delta = \sum_{i=0}^{PMR-1} 2^i \cdot RTO \quad (3)$$

Generally, the failover time using default SCTP settings is likely to be unacceptable to users. Shortening this time can be achieved by setting the relevant protocol parameters (e.g.,  $RTO.Min$ ,  $RTO.Max$ ,  $PMR$ ) to smaller values.

When the primary address becomes unreachable or the link conditions are not acceptable, alternative IP address should be used if the endpoint is multihomed. With the

heartbeat mechanism the SCTP knows which other addresses are active or not and thus, can avoid using another path that has a failure.

Using SCTP the mobility means the ability to change the endpoints and IP addresses while keeping the end-to-end connection. The change of communication link should be done with minimal disruption to the data transmission in progress. The multiple interface concepts can be utilised in dynamic mobile networks where e.g., the host terminal has only one interface but the connection is frequently changed. If the possible IP addresses are known they can be bound even at connection setup. Using the early IP address bindings, the handovers can be handled in such way.

Mobile SCTP (mSCTP) (Stewart et al., 2007) is an extension of the SCTP in order to support mobility more efficiently. The mSCTP protocol utilises the functions to dynamically add or delete IP addresses for an existing connection in order to support mobility.

### 3.5 UMTS–WLAN architecture basics

One of the main features of next generation communication architectures evolving toward 4G and beyond is the inter-operation of multiple radio access technologies such creating heterogeneous networks. In general, today's heterogeneous systems tend to apply a core layer which deals with all network functionality and operates a single network to the upper-layer protocols. Therefore, different radio access technologies implement only the physical and link layer functions where each function is specialised to the appropriate technology, and a common language (the internet protocol) provides integration.

Access technologies differ in their physical layer, medium access control and link-layer protocols, because different methods are needed to meet different requirements of the physical medium (i.e., local- or wide-area coverage). Consequently, user experience in a 3G UMTS cellular network is quite different from 802.11a/b/g/n WLANs. These differences constitute the complementary characteristics of 3G UMTS and WLAN technologies in the means of service coverage, available bandwidth, RTT, modulation, roaming, FEC, deployment and service costs, etc., such making the integration of these coping architectures very promising (see Table 1 for details).

**Table 1** Complementary characteristic of UMTS and WLAN

<i>Parameter</i>	<i>Access technology</i>	
	<i>3G UMTS</i>	<i>802.11a/b/g/n</i>
Coverage	Wide-area (15–20 km)	Local-area (50–800 m)
Data rates	Low (up to 2 Mbit/sec)	High (5–500 Mbit/sec)
RTTs	High (150–500 ms)	Low (5–50 ms)
Security	Strong (e.g., AKA)	Relatively weak (e.g., WPA-PSK)
Mobility	Link-layer	Layer 3
Cost	High	Low

UMTS provides always-on wide-area radio access scheme with high user-mobility support, relatively low offerable data rates and high deployment and service cost, while WLAN networks cover only small, local-areas and present much higher data rates with lower user-mobility support, lower deployment and service cost.



3GPP TSG SA1 workgroup defined six different levels for the UMTS-WLAN inter-working (3GPP TR 22.934 V7.0.0, 2007). Each level describes the next step on the integration path of open/loose/tight coupling the different access technologies while setting up a flexible and scalable framework to realise full cooperation. The complexity of the inter-working scheme increases from level one to level six. In level one the cooperation between the two systems does not effect the two systems too much as only billing and customer care have been united. The second level provides 3GPP system-based access control and charging while the third level introduces the IP level cooperation between the WLAN and UMTS system, thus, packet switched services in UMTS are available from the WLAN network as well. However, this third level does not prevent discontinuity of services when performing a handover. Thus, level four grants the continuity of services while level five assures seamless operation. In case of the sixth level of cooperation even the circuit switched services are made available and handovers cannot be identified any more.

#### **4 Testbed architecture**

In order to provide an IPv6-capable heterogeneous testbed for analysing SCTP multihoming in next generation multi-access communication systems, we designed and implemented a native IPv6 UMTS–WLAN architecture based on the existing hardware elements of mobile innovation centre (MIK) located in Budapest, Hungary. However, almost all the relating hardware and software components were presented in MIK, one important item was missing: the laboratory did not possess any dedicated gateway GPRS support node (GGSN) device for supporting native IPv6 UMTS access. Thus, one of our main tasks during the implementation of our native IPv6 UMTS–WLAN testbed aiming to perform extensive SCTP multihoming performance measurements was to design and develop a GGSN, prepared to be integratable with the other UMTS elements and adequate to handle IPv6 type packet data protocol (PDP) contexts as well. In order to achieve this, we used a software GGSN implementation called OpenGGSN as a basis of our work.

OpenGGSN was originally developed to provide a full GPRS tunnelling protocol (GTP) (3GPP TS 29.060 V8.5.0, 2008) implementation for the open source community of Unix systems. The last version was released under GNU GPL in 2004 with version number 0.84 written in standard C programming language. The main part of OpenGGSN 0.84 is the GTP library, the GGSN implementation using the GTP library and a service GPRS support node (SGSN) emulator for testing purposes. The GTP library implements both of GTPv0 and GTPv1 specifications. The GGSN module handles IPv4 PDP contexts with two different address allocation schemes (static and dynamic) and uses virtual TUN interfaces for delivering user data. QoS management is totally missing from the original version. The SGSN emulator handles also only IPv4 type PDP contexts.

Our GPL licensed and publicly available OpenGGSN modification is based on the above software components: OpenGGSN 0.84\_v6\_03 (Setting up native IPv6 3G UMTS) uses the same GTP library and the main architecture as version 0.84, but extends the original edition with the missing IPv6 routines, some other related components and also with functions making the software to be able to cooperate with HUAWEI SGSN 9810 serving GPRS support node for setting up, maintain and tear down contexts of native

IPv6 UMTS communication. All the organic procedures required for the basic standard operations of an IPv6 UMTS system were implemented in our GGSN version. However, due to time constraints and lack of resources we had to take advantages of some simplification possibilities during the design of our IPv6-capable GGSN software in order to reduce the development time and other requested expedients. These simplifications are mainly connected to the address allocation procedures and the QoS-related functions. Despite the fact that the recommendation of Yoo et al. (2003) says that GGSN should be able to allocate different IPv6 prefix(es) to different UEs thus, making possible to link more the one prefix to one PDP context (i.e., single-access multihoming support over 3G), OpenGGSN 0.84\_v6\_03 does not support this kind of behaviour. The management of different address pools and the QoS provisioning functions are also missing: pre-set link-local address, prefix and resources can only be assigned to the UE sending an activate PDP context request message. All of these limitations and known issues (together with our main adjustments and fixes) are precisely detailed in Setting up native IPv6 3G UMTS. Despite the fact of the currently existing limitations, our work-in-progress, open source IPv6-capable software GGSN platform provides a highly configurable 3G testing environment making possible to observe, measure and even modify every kind of GGSN function, traffic or operation.

The integration of our IPv6-compatible GGSN software into a compact, loosely-coupled IPv6 UMTS–WLAN testbed architecture was a six-step procedure. First, we had to create a new, IPv6-compatible APN in the SGSN, than we had to enable IPv6 PDP contexts for the SIM cards of our devices in the home subscriber server (HUAWEI HSS 9820). After that we compiled, configured and started all the required OpenGGSN 0.84\_v6\_03 components on a SunFire X4200 running Ubuntu 7.04 (Feisty Fawn) with kernel 2.6.23. As the 4th step we deployed an UMTS–WLAN integrated authentication system managed by a radius server applying EAP-TLS in order to provide 3GPP system-based access control. Step no. 5 was the configuration of end terminals, while the last step was setting up the appropriate IPv6 routing entries in the routers of the testbed in order to provide GEANT connection to the mobiles. Figure 1 shows all the details of the integrated, native IPv6 UMTS–WLAN architecture we used for our SCTP multihoming experiences.

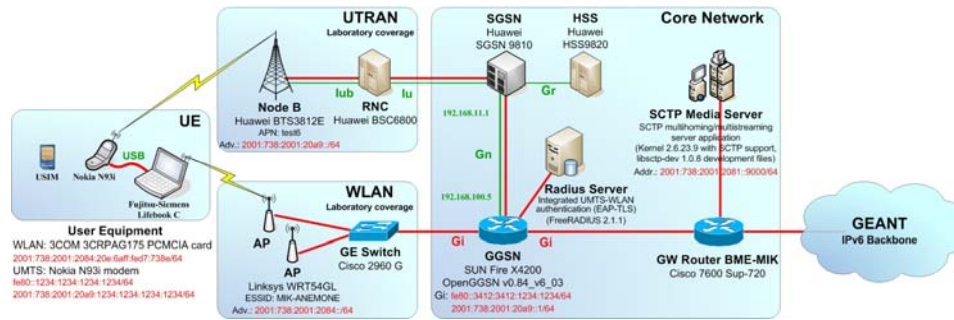
In this testbed, the UMTS infrastructure consists of one Node B and one RNC linked to the SGSN which is connected to the GGSN and the HSS using standard interfaces. As Figure 1 shows, the SGSN and the GGSN are still communicating over IPv4 (i.e., the GTP tunnels are set up on IPv4), but this fact has no effect on the UE's native IPv6 UMTS connection: the mode of communication between the GSN nodes does not have any impact on the fact that the 3G users are gaining native IPv6 UMTS experience. The GGSN is connected to the Radius server, to the WLAN access component and to the outside network through its Gi interface using native IPv6 transport. The UMTS component enables IPv6 services at maximum 2 Mbit/sec download and 384 Kbit/sec upload speeds with RTTs around 180 ms. The WLAN connectivity comprises IEEE 802.11 b/g compatible Linksys WRT54GL access points. This exclusive, local wireless access enables UE to maintain native IPv6 connection with data rates up to 28 Mbit/sec and RTTs around 10 ms.

For accessing this native IPv6 UMTS–WLAN architecture, UE has been equipped with two separate interfaces for WLAN and UMTS access respectively. UE's hardware is based on Fujitsu-Siemens Lifebook C1110D with a 3Com 3CRPAG175 PCCARD

WLAN adapter featuring Atheros<sup>R</sup> chipset, and a Nokia N93i SmartPhone as an IPv6-compatible 3G modem for UMTS connectivity.

The SCTP media server is a standard PC with a 4GHz Pentium 4 processor and 1024 MB RAM, running a C implementation of our SCTP-based media server application supporting multihoming/multi-streaming features and also measurement functions.

**Figure 1** SCTP multihoming testbed in a loosely-coupled, native IPv6 UMTS–WLAN architecture (see online version for colours)



## 5 Experimental results

In this section, the measurement results of different test scenarios are introduced. SCTP has a large number of adjustable association and path parameters that can be modified using *setsockopt()* kernel function. Applications use *setsockopt()* and *getsockopt()* to set and retrieve socket options respectively. These socket calls are used to change different socket options.

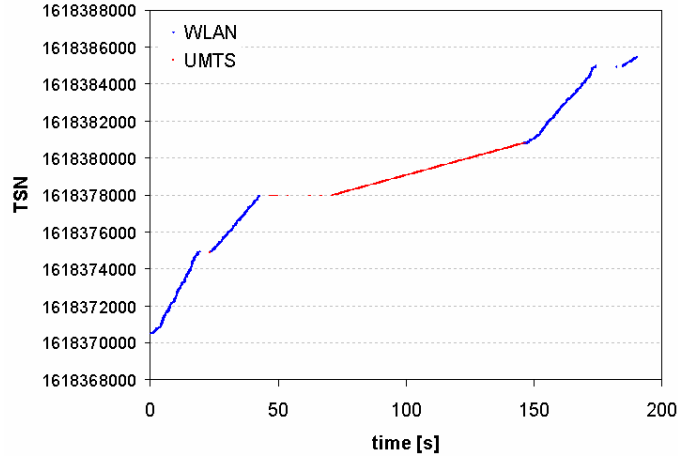
We have focused our measurements on SCTP handover behaviour. Our goal was to analyse the effect of different protocol parameter settings on the handover process. However, the handover also depends on the network environment. The tests were made in the native IPv6 UMTS–WLAN environment introduced in the previous section.

In the first scenario the multihoming feature of the SCTP protocol was investigated. We have examined the SCTP multihoming performance in a considered situation where the user has WLAN and 3G UMTS connections simultaneously. The default and primary connection is the WLAN because it provides higher bandwidth, lower latency and not at least it is cheaper than the communication over UMTS network. Therefore, the primary address was always belonging to the WLAN interface. The considered scenario was that the user is using its UMTS connection only if WLAN is not available. As the WLAN is accessible again, the communication path is to be changed back to the WLAN interface. In order to effectively introduce the considered scenario we have illustrated the transmission sequence number (*TSN*) versus time on Figure 2. Each DATA chunk corresponds to one plot. The DATA chunks that were transmitted through the WLAN interface are depicted in blue, while the DATA chunks delivered in the UMTS network is red.

WLAN networks have more transmission capacity, which is also visible in Figure 2. The slope of the blue curve (WLAN) is higher than the red one (UMTS). It is noticeable when the handover occurs from WLAN to UMTS the data communication is not

continuous. The SCTP stack needs time to recognise that the primary path is not available any more. It also needs time to retransmit the lost packets and reach the available UMTS bandwidth. The other direction (UMTS  $\rightarrow$  WLAN handover) is faster because neither link failure detection nor data retransmission is needed.

**Figure 2** Transmission sequence number (TSN) versus time (see online version for colours)



Notes:  $HB.Interval = 10$  s,  $RTO = 4,000$  ms,  $Path.Max.Retrans = 5$

The most important protocol parameters from the handover point of view are  $RTO.Min$ ,  $RTO.Max$  and  $Path.Max.Retransmission$  ( $PMR$ ). These parameters, and the continuously calculated  $RTO$  value determine the speed of the handover. We have set  $RTO.Min = RTO.Max$  therefore, the  $RTO$  was kept on a constant value disabling to redouble it every time when timeout occurs, see equation (3). In such way the handover process can be speed up. The delay of the path failure recovery and the handover process in this case can be calculated as follows:

$$\Delta = PMR \cdot RTO \quad (4)$$

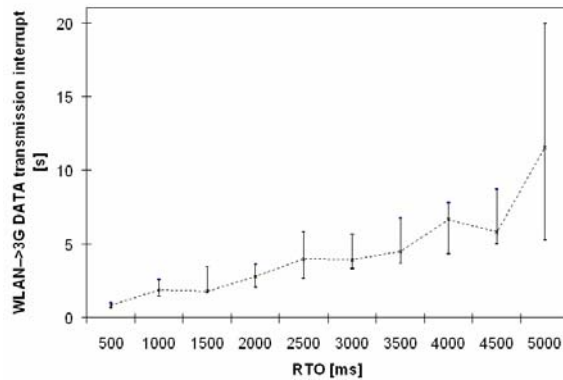
The negative effect of this solution is that the  $RTO$  must be set manually by adjusting  $RTO.Min$  and  $RTO.Max$  parameters, therefore, the SCTP will lose its adaptability to the link changes.

In order to analyse the effect of  $RTO$  on the handover process we have measured DATA transmission interrupt that is considered as the elapsed time between the last DATA chunk sent on the failing primary (WLAN) interface and the first DATA chunk arrived at the continuously available secondary (UMTS) interface (Figure 3). The level of seamlessness depends on this delay. We have made more measurements to eliminate to variance of the measured values (the min, max and average values are illustrated in the figures).

The other important parameters from the handover point of view were set as follows:  $HB.Interval = 10$ s,  $PMR = 5$ . The results fulfil our expectations because the delay is rising linearly when the  $RTO$  is incremented. Using the default SCTP parameters ( $RTO.Min = 1$ s,  $RTO.Max = 60$ s) the delay would rise exponentially due to  $RTO$  redoubling. We have also measured the DATA transmission interrupt with default SCTP parameters. The average handover delay was 227s, which is not acceptable for the users.

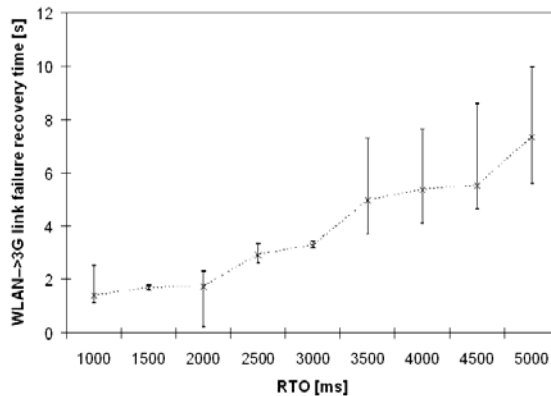
The link failure recovery time and the previously presented DATA chunk transmission delay measurements are very similar. In means of link failure recovery time we have analysed how fast the path failures can be recovered. The recovery time is considered as the time difference of the first DATA chunk on the new path and the old link failure. As Figure 4 shows as high the *RTO* value is as long time is needed from the link failure till DATA chunk appears on the secondary link. (Note that here *RTO.Min* = *RTO.Max* was set, therefore, the *RTO* was kept constant.)

**Figure 3** The impact of the *RTO* on the DATA transmission interrupt



Note: WLAN → 3G UMTS handover

**Figure 4** The impact of the *RTO* on the link failure recovery time

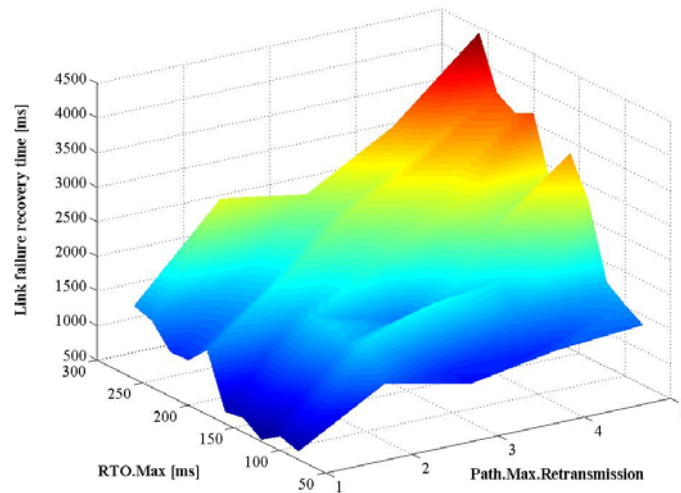


Note: WLAN → 3G UMTS handover

We have also analysed the backward direction, when the primary link (WLAN) becomes available again. We found that the link availability recognition time needed to recognise that the WLAN is available again is independent from the *RTO*. The link availability recognition time is considered as the time elapsed from the link appearance till the first DATA chunk on it. The *RTO* variable has impact only on the link failure recovery time, because *RTO* time is needed without acknowledging the packet to consider a datagram as a lost one.

Besides *RTO*, the *PMR* (*Path Max. Retransmission*) is the other key parameter of the SCTP handover. *PMR* contains the maximum number of retransmissions before this address shall be considered unreachable. Using the default parameters of the protocol the link failure recovery time is rising exponentially according to (3). In Figure 5 the joint impact of *RTO.Max* and *PMR* is presented.

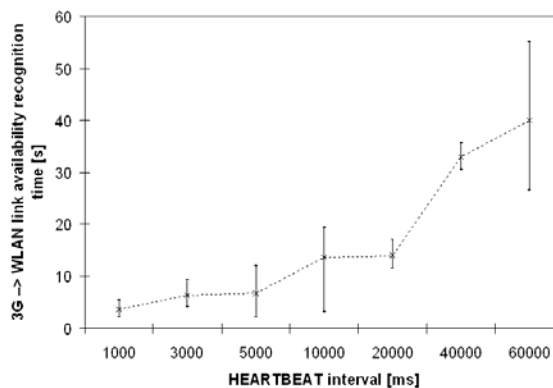
**Figure 5** The impact of the *RTO* and *PMR* on the link failure recovery time (see online version for colours)



Note: WLAN → 3G UMTS handover

The SCTP heartbeat mechanism is responsible for detecting when the primary path has recovered. HEARTBEAT chunks are sent periodically as defined by the *HB.Interval* and the corresponding equation, see (1). To discover that the primary path becomes available (link availability recognition time), it is desirable to keep the interval between HEARTBEATS relatively small. The obtained measurement results confirm this theory as Figure 6 shows.

**Figure 6** The impact of the HEARTBEAT interval on the link availability recognition time

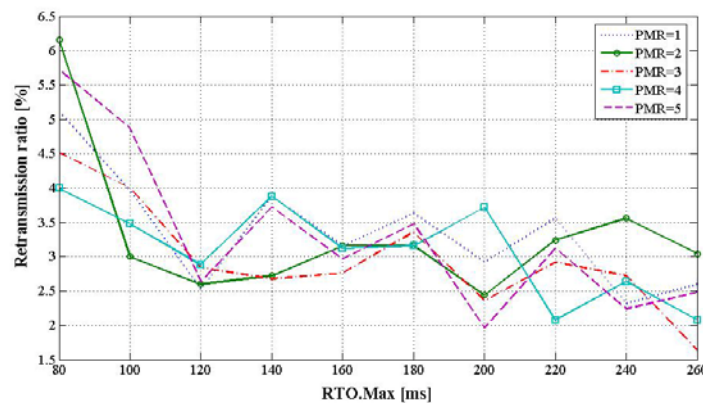


Note: 3G UMTS → WLAN handover

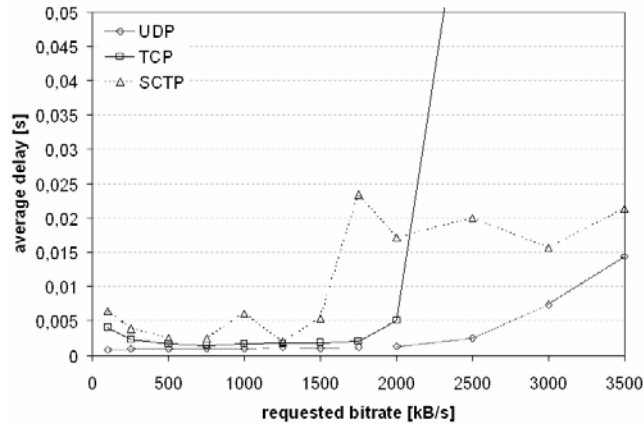
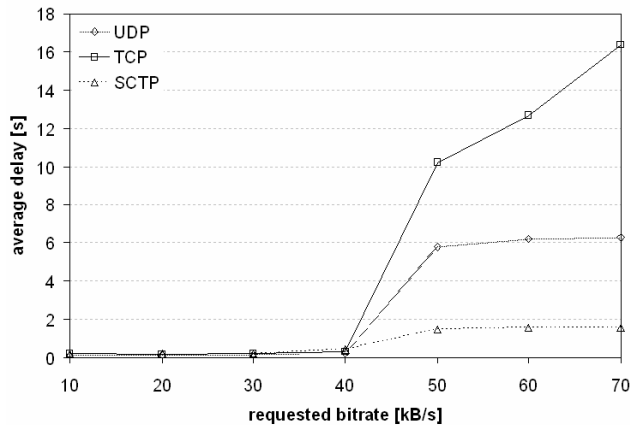
When changing the communication path back to the primary path, the first packet on the primary link is always a HEARTBEAT chunk. The DATA chunk can be delivered only if HEARTBEAT-ACK is received. The link failure detection is independent from the *HB.Interval* parameter.

SCTP is a reliable transport protocol; hence, all the lost packets must be retransmitted. Packet losses can not be avoided if the active link becomes unavailable. If the handover process time is too long, the number of lost packets can increase significantly. Previously we have presented that increasing the value of the *RTO.Max* parameter the link failure recovery time will also increase (Figure 5), however, the number of retransmitted packets will be reduced. Obtained results presented in Figure 7 show that if the retransmission timer (*RTO.Max*) is set to low values, the lost packet will be tried to be retransmitted more frequently.

**Figure 7** Retransmission ratios (see online version for colours)



We have analysed the performance of SCTP with respect to delay, jitter and throughput with different traffic loads (Figure 8). Comparative analysis was made between SCTP and both TCP and UDP. The traffic between the two SCTP hosts was delivered as one stream. We used D-ITG packet-level traffic generator to produce traffic flows and to perform measurements. D-ITG can be used to analyse throughput and jitter at the packet level, and also to measure the RTT delay and the one-way delay. In order to correctly measure the delay of the transmission precisely synchronised endpoints are needed. We have used network time protocol (NTP) for this purpose. The offset of the two endpoints' system clock was acceptable for the delay measurements in both WLAN and UMTS transmissions. In our testbed the average RTT in WLAN was 1.019ms, while the standard deviation was 0.66 ms according to the *ping6* tool. Using the UMTS interface the measured RTT was 207.94ms with 119.929ms standard deviation. When the requested bit rate becomes higher than the available bit rate of the used access technology, the delay of packet delivery is increasing. The highest delay belongs to TCP due to its congestion control mechanism and the retransmissions of the lost packets. UDP is the protocols that presents the lowest delay and jitter in all cases, while SCTP presents intermediate delay and jitter values. SCTP congestion control provides lower bit rate but lower delay as well. The sudden increase of the delay appears when the network becomes congested.

**Figure 8** The average transmission delay of UDP, TCP and SCTP in our native IPv6 WLAN environment**Figure 9** The average transmission delay of UDP, TCP and SCTP in our native IPv6 UMTS environment

We have also compared the transport protocols in native IPv6 WLAN and UMTS networks from the throughput point of view (Figure 10 and Figure 11). According to the protocol RFCs we have expected similar behaviour because SCTP and TCP adopt the same congestion and flow-control scheme, with the exception of the fast recovery mechanism used by TCP. The current specification of SCTP's congestion control causes performance degradation when there are multiple packet losses in a single window. Our measurements confirm this degradation.

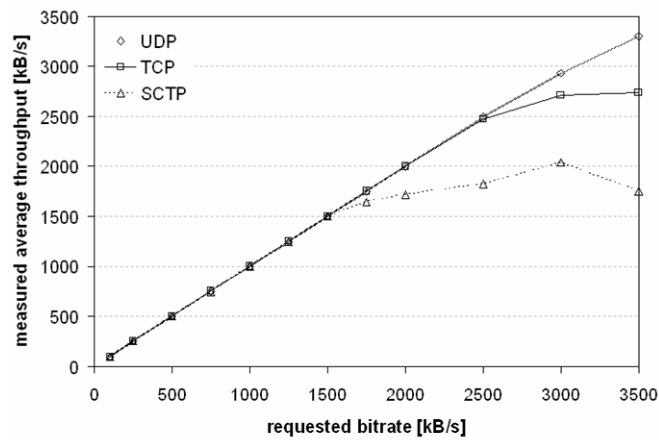
In order to measure the throughput effectiveness of the protocols we have injected synthetic traffic into our testbed with the D-ITG tool and measured the throughputs. The highest bit rate was reached by the UDP because it does not use congestion controlling and retransmissions. On the other hand, UDP suffers from significant packet loss rates. In the competition of the congestion controlled and reliable protocols the TCP seems to have a better control of congestion and it can serve higher bit rate. From the throughput point of view the SCTP has the worst performance. It could not even reach the available



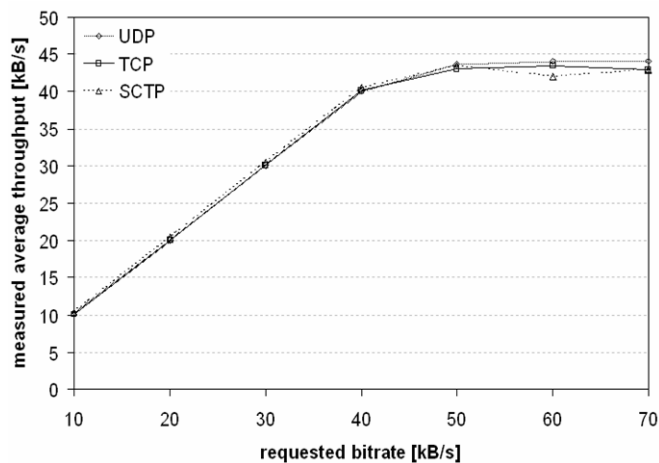
capacity of the WLAN links. In our measurements the TCP throughput was about 20%–30% higher than the SCTP throughput above 1,500 kB/s offered bit rate. The breakpoint of the throughput curve was 1,500 kB/s in case of SCTP, while 2,500 kB/s in case of TCP.

At lower bit rates the difference of operation of the congestion control algorithms of TCP and SCTP is not significant. As Figure 11 shows all protocols were performing similarly. Using UDP, the first packet loss appeared at 50 kB/s requested bit rate, while at 70 kB/s the packet loss rate was 33.82%.

**Figure 10** The average throughput of UDP, TCP and SCTP in our native IPv6 WLAN environment



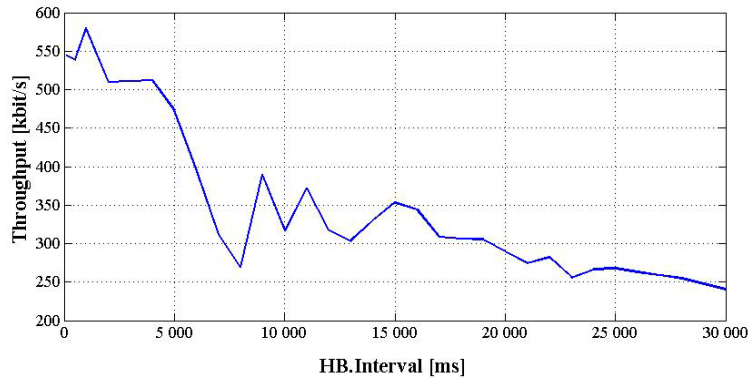
**Figure 11** The average throughput of UDP, TCP and SCTP in our native IPv6 UMTS environment



In our testbed, the performance of SCTP was comparable to the other protocols only under low packet rate conditions. According to the delay measurements, when the packet rate increases TCP reaches congestion later than SCTP.

In the throughput measurements introduced above we analysed SCTP behaviour over distinct WLAN and UMTS networks where only the link properties were affecting SCTP performance. In Figure 12 we present SCTP throughput measurement results gathered during handover scenarios where an ongoing 3G connection is switched over to an appearing WLAN network. In such a use-case *HB.Interval* is the key protocol parameter controlling the speed of relocating SCTP data packets towards the new network.

**Figure 12** Throughput in function of *HB.Interval* (see online version for colours)



Note:  $PMR = 2$ ,  $RTO.Max = 180\ ms$

*HB.Interval* defines the frequency of HEARTBEAT messages sent to secondary links of an SCTP session. As Figure 6 shows, frequent HEARTBEAT messages decrease the time needed to recognise newly appearing links during an ongoing communication. If the link availability detection takes place quickly, the communication can start earlier in the WLAN segment offering higher bit rates such the overall throughput could be enhanced. However, frequent HEARTBEATs are able to provide this advantage; their overhead should be taken into consideration as well. Figure 12 shows the gain of quick link-availability recognition. Despite the fact that small *HB.Interval* values results higher SCTP signalling overhead, SCTP still performs much better in terms of throughput. It means that the negative effects of frequent HEARTBEATs are vanished by the benefits of fast link-availability recognition provided by them.

## 6 Conclusions

In this paper we presented an experimental analysis of SCTP in wireless environment in terms of handover effectiveness, throughput and transmission delay. The measurements were done in a loosely-coupled UMTS-WLAN heterogeneous network supporting native IPv6. The multihoming behaviour of SCTP is an advantageous feature of the protocol, however, its performance highly depends on the parameter settings. In our measurements we have analysed numerous settings to justify the analytical correlations of the protocol parameters and the different transmission characteristics. Using accurate SCTP parameter setup, the handover delay and the data transmission interrupt can be significantly decreased. We also compared SCTP with TCP and UDP in terms of throughput in native IPv6 WLAN and 3G UMTS networks. The obtained results showed that the SCTP

throughput in UMTS network was similar to other transport protocols, while in WLAN, which offers higher throughput capacity, the performance of SCTP was lower than the other examined protocols. Our future plan is to make recommendations on suitable SCTP parameter configurations in order to minimise the handover delay and maximise the throughput in heterogeneous IPv6 networks. We also would like to analyse the effect of different link characteristics (network delay, loss rate, etc.) on the performance of SCTP.

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