

Differential Non-linearity, Integral Non-linearity, and Signal to Noise Ratio  
 of an Analog to Digital Converter  
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4. A simple Analytic Model on INL and SNR

SFDR (THD)

In this section, an analytical model for the INL is proposed. A group of cubic curves are considered to represent the transfer functions of ADC. The function of the curve is given by  $y = ax^3 + bx^2 + cx + d$ . Using the property that the transfer function of an ADC has a full scale range of 2, three points contained in the curve are:  $(-1, -1)$ ,  $(0, 0)$  and  $(1, 1)$ . Hence, the function is  $y = ax^3 + (1-a)x$ . By changing the value of the coefficient 'a', we can obtain a group of curves with different features.

Cubic BOW (S curve)

endpoint INL (offset and gain NULLIFIED)

According to the definition of INL, it is the maximum deviation of the curve from the line,  $y=x$ . The deviation between the curve and the line,  $y=x$ , can be represented by  $D(x) = x - (ax^3 + (1-a)x) = ax - ax^3$ , and a local maximum happens when  $D'(x) = 0$ , i.e.,  $x = 3^{-1/2}$ . Therefore, at that point we have  $INL = a(3^{-1/2} - 3^{-3/2})$ .

@ n-bit ADC:

$$\max INL_{LSB} = \frac{a \cdot \frac{2}{3 \cdot \sqrt{3}}}{(2/2^n)}$$

Suppose a sine wave,  $x = \sin(\omega t)$ , is digitized by an ADC with the transfer function  $y = ax^3 + (1-a)x$ , then the output is

$$y = a \sin^3(\omega t) + (1-a)\sin(\omega t)$$

$$= (1-0.25a) \sin(\omega t) - 0.25a \sin(3\omega t) \quad (2)$$

$$HD3 = \frac{a}{4-a} \approx \frac{a}{4} \quad a \ll 1$$

SFDR<sub>dB</sub>

From Equation 2, the SNR of output is

$$SNR = 20 \log_{10} [(4-a)/a]$$

$$= 20 \log_{10} (1/HD3)$$

$$\approx 20 \log_{10} (2^n / \max INL_{LSB})$$

3<sup>rd</sup> order Harmonic Distortion

Example: n = 10 bits,  $\max INL_{LSB} = 1 \rightarrow SFDR_{dB} \approx 60$ .

Note:  $SQNR_{dB} = 6.02 \cdot n + 1.76 \approx 6 \cdot n + 1.8$

@ 2<sup>m</sup> point FFT:  $SNR_{dB} = NoiseFloor_{dB} - 3 \cdot (m - 1)$

Nº of bits:  $n := 10$      $\Delta := \frac{2}{2^n}$

**cubic BOW (S curve):**

$a := 0.0051$      $y(x) := (1 - a) \cdot x + a \cdot x^3$      $INL(x) := \frac{y(x) - x}{\Delta}$      $maxINL := \frac{2 \cdot a}{3 \cdot \sqrt{3}} \cdot \frac{1}{\Delta}$

**sine input,**

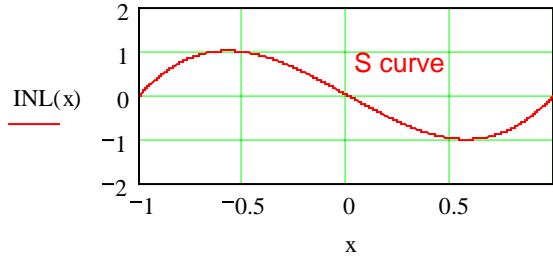
**4K FFT:**     $m := 12$      $S := 2^m$      $i := 0..S - 1$

$maxINL = 1.005$

$L := 201$      $x_1 := \sin\left(2 \cdot \pi \cdot \frac{L}{S} \cdot i\right)$

$Qy_i := \Delta \cdot \text{round}\left(\frac{y(x_1)}{\Delta}\right)$

$c := \text{FFT}(Qy)$

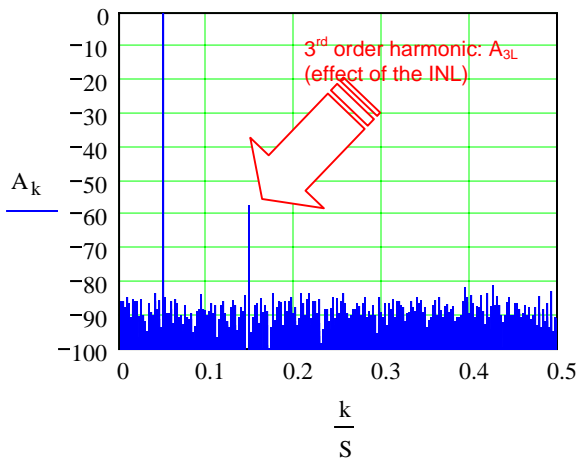


$M := \text{last}(c)$      $k := 0..M$      $dBV_k := 20 \cdot \log\left(\sqrt{2} \cdot |c_k| + 10^{-10}\right)$

$A_k := dBV_k - dBV_L$

$A_L = 0$

$A_{3 \cdot L} = -57.734$



**THD:**

$THD := 20 \cdot \log\left(\frac{a}{4 - a}\right)$

$THD = -57.879$

**SFDR:**

$SFDR := 20 \cdot \log\left(\frac{2^n}{maxINL}\right)$

$SFDR = 60.162$

**Noise Floor:**     $NFI := \frac{1}{M - 2} \cdot \left[ \sum_{k=1}^{M-1} 2 \cdot (|c_k|)^2 \right] - 2 \cdot \left[ (|c_L|)^2 + (|c_{3 \cdot L}|)^2 \right] + (|c_M|)^2$

$NoiseFloor := 10 \cdot \log(NFI) - dBV_L$

$NoiseFloor = -95.122$

**SNR:**

$SNR := -NoiseFloor - 3(m - 1)$

$SNR = 62.122$

**SQNR:**

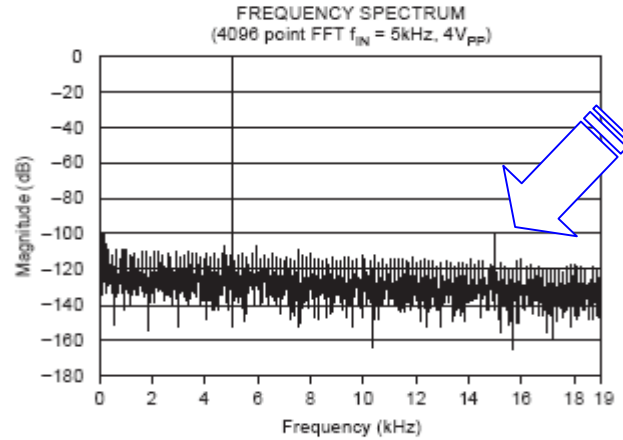
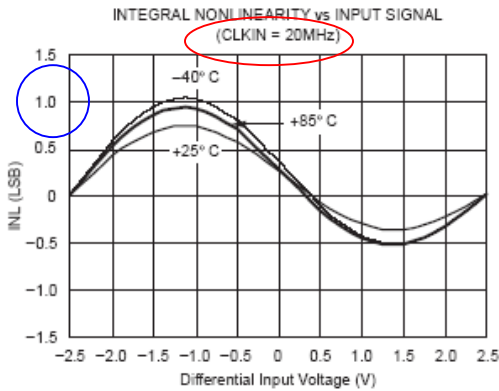
$SQNR := 6.02 \cdot n + 1.76$

$SQNR = 61.96$

# ADS1204: 16-bit resolution, 14-bit linearity

## TYPICAL CHARACTERISTICS

AV<sub>DD</sub> = 5V, BV<sub>DD</sub> = 3V, CH x+ = +0.5V to +4.5V, CH x- = +2.5V, REFIN = external, CLKSEL = 0, and 16-bit Sinc<sup>3</sup> filter, with OSR = 256, unless otherwise noted.



## ELECTRICAL CHARACTERISTICS

Over recommended operating free-air temperature range at -40°C to +85°C, AV<sub>DD</sub> = 5V, BV<sub>DD</sub> = 3V, CH x+ = 0.5V to 4.5V, CH x- = 2.5V, REFIN = REFOUT = internal +2.5V, CLKIN = 20MHz, and 16-bit Sinc<sup>3</sup> filter with decimation by 256, unless otherwise noted.

PARAMETER	TEST CONDITIONS	ADS1204I			UNITS
		MIN	TYP(1)	MAX	
Resolution		16			Bits
DC Accuracy					
INL	Integral linearity error(2)		±1	±3	LSB
			±0.001	±0.005	% FSR
	Integral linearity match			6	LSB
				0.009	% FSR

## ELECTRICAL CHARACTERISTICS

Over recommended operating free-air temperature range at -40°C to +85°C, AV<sub>DD</sub> = 5V, BV<sub>DD</sub> = 3V, CH x+ = 0.5V to 4.5V, CH x- = 2.5V, REFIN = REFOUT = internal +2.5V, CLKIN = 20MHz, and 16-bit Sinc<sup>3</sup> filter with decimation by 256, unless otherwise noted.

PARAMETER	TEST CONDITIONS	ADS1204I			UNITS
		MIN	TYP(1)	MAX	
Resolution		16			Bits

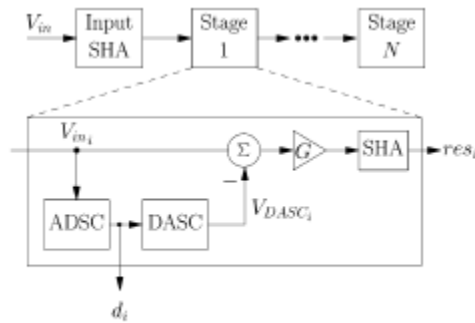
AC Accuracy					
THD	Total harmonic distortion	V <sub>IN</sub> = ±2V <sub>pp</sub> at 5kHz	-96	-88	dB
SFDR	Spurious-free dynamic range	V <sub>IN</sub> = ±2V <sub>pp</sub> at 5kHz	92	100	dB
SNR	Signal-to-noise ratio	V <sub>IN</sub> = ±2V <sub>pp</sub> at 5kHz	86	89	dB
SINAD	Signal-to-noise + distortion	V <sub>IN</sub> = ±2V <sub>pp</sub> at 5kHz	85	89	dB
	Channel-to-channel isolation(3)	V <sub>IN</sub> = ±2V <sub>pp</sub> at 50kHz	85		dB
ENOB	Effective number of bits		14	14.5	Bits

$$20 \cdot \log\left(\frac{2^{14}}{1}\right) = 84.288$$

$$20 \cdot \log\left(\frac{2^{16}}{1}\right) = 96.33$$

# A 12-bit 80-MSample/s Pipelined ADC With Bootstrapped Digital Calibration

Carl R. Grace, Paul J. Hurst, *Fellow, IEEE*, and Stephen H. Lewis, *Fellow, IEEE*



Block diagram of pipelined ADC.

Each stage except the last contains an analog-to-digital subconverter (ADSC), a digital-to-analog subconverter (DASC), an analog subtracter, and a SHA with gain  $G$ .

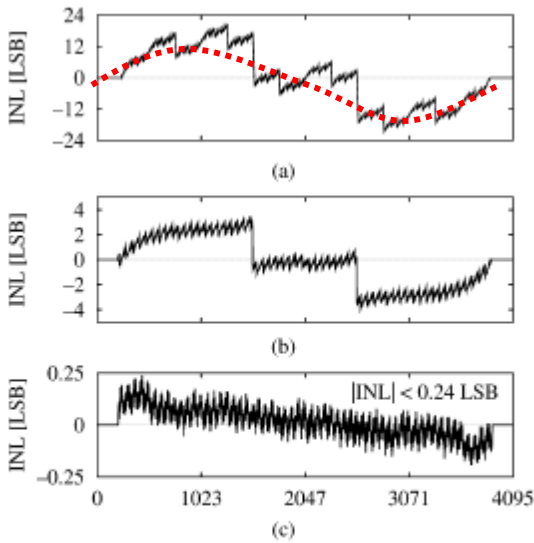


Fig. 14. INL with foreground calibration: (a) with no calibration, (b) with constant-gain calibration only, and (c) with full calibration. Sampling rate is 80 MS/s.

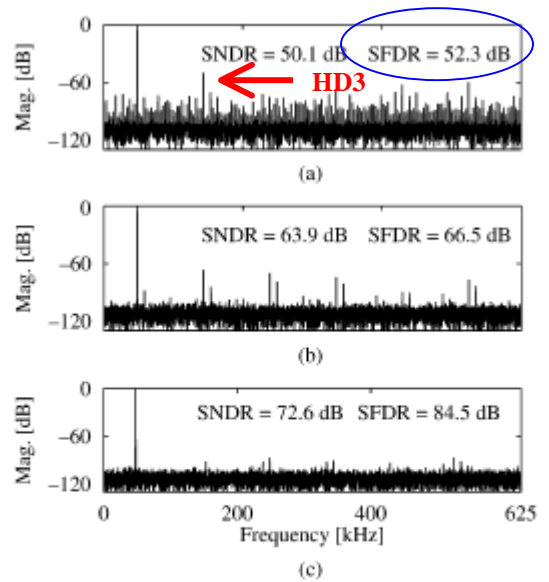


Fig. 15. ADC output spectra with foreground calibration: (a) with no calibration, (b) with constant-gain calibration only, and (c) with full calibration. Sampling rate is 80 MS/s. Output downsampled by factor of 64.

$$20 \cdot \log \left( \frac{2^{12}}{13} \right) = 49.97$$